

Presentation Overview



- Background
- Decision Aiding System (DAS)
- Designing a DAS
- Results
- Summary

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Types of Intelligent Systems



<u>Coaches</u> try to make you better at what you do



Associates automatically help with tasks

Assistants do what you ask them to do

Experts do what they know how to do



Understanding Built on Data



Simulation

Probability of Success

Probability of Kill

Probability of Survival

Models

Enemy Intent

Plan/Goal Graph Fly Out Models

Signature Management

Concepts

Threat Templates

Networked Threats

Weapon Release Signature Notch

Derived Information

Target Position

Threat ID

Route Exposure

Fused Data

Target Location

Geo-located SAR Image

Threat Position

Dynamic Data

RADAR Strobes SAR Image AV Position Weapons Load Route Plan

Static Data Files

Terrain Data

Threat/Target Characteristics

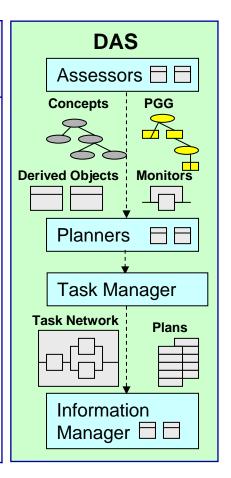
RF / IR Signatures

Assessment

Decision Aiding System (DAS) Functionality Overview

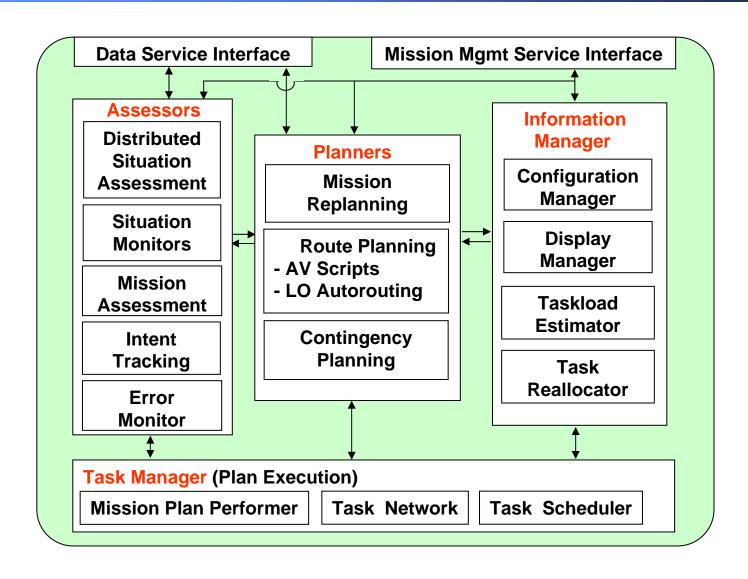


Assessors	Planners	Task Manager	Information Manager
Monitor mission.	Provide weapon allocation to targets.	Task Network equivalent to a	Bring up displays or specific pages.
Detect new threats. Assess route impact.	Evaluates mission plan alternatives with different defining parameters.	manager's PERT chart to coordinate activities. Temporal task model of	Pan/zoom about proposed mission plans.
Trigger replanning.	Type (ATK, SAR, etc.)Target	operator and computer tasks.	Bring up weapon pairing/LAR ymbols.
Monitor mission plans. Monitor status.	Weapon type/ number	Tasks prioritized by task importance and deadline.	De-clutter unwanted symbols.
	Recommends new mission plan. Operator can apply or cancel recommended	Operator task drives displays via information requirements.	Locate secondary window text in open corners.
	plan.	Computer tasks drive automation.	Prioritize alerts.
			Reallocate tasks.



Decision Aiding Notional Software Architecture







Step	Product	Tool
Identification of knowledge requirements	Requirements Document, Knowledge Engineering Plan	Requirements Engineering tool such as DOORS
Production of the domain ontology for the domain of interest	Domain Ontology	Relational Database
Production of system knowledge at an intermediate level of representation	Intermediate Representation Forms- Contains activities such as Plans, Goals, Graphs, and Tasks	Integrated Knowledge Environment (IKE)
Conversion of this intermediate level representation to operational knowledge	Knowledge Base File containing the Operational Knowledge Representation	IKE
Testing of this knowledge to validate it	Validated Knowledge	Test Plans, Models, and Simulations



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Domain Ontology (Definition)



do·main: a sphere of knowledge, influence, or activity

on·tol·o·gy: a particular theory about the nature of being or the kinds of existents

"What things exist in your sphere of knowledge"

Unmanned Combat Air Vehicle Flight Operations

Domain Ontology (Knowledge Categories)



Air Vehicle Physical Description

Airspace Zones and Areas

Aviation Aircraft Operations and Performance

Communications Radios and IFF

Formulary Mathematical Formulas

Mapping, Charting, Geodesy and Imagery

Navigation

Mission Planning Flight Planning plus Target Engagement

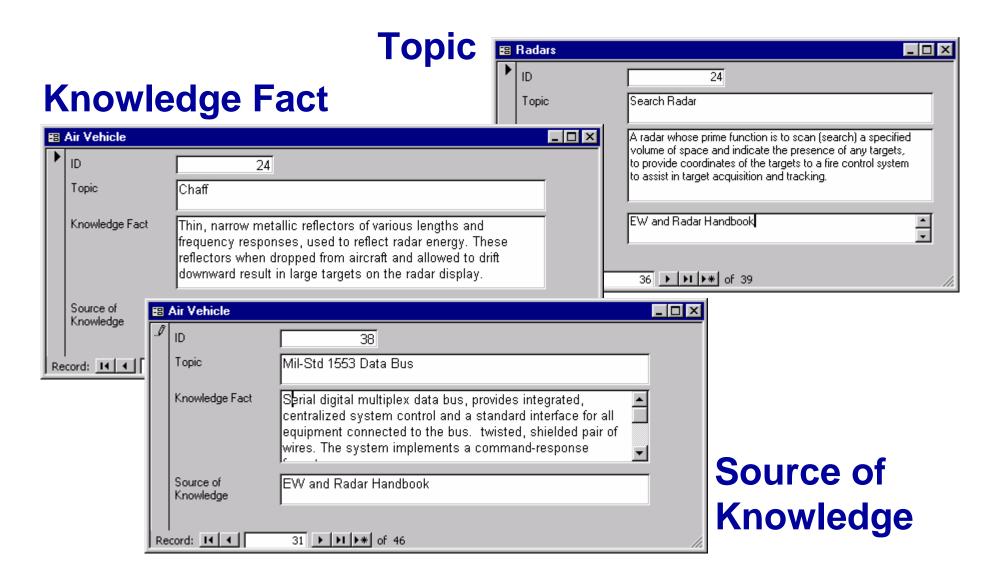
Radar ESM and SAR

Roles and Missions Aircraft Roles and Combat Missions

Weapons Air-to-Surface and Surface-to-Air

Relational Database Organizes Domain Ontology





Domain Ontology Representation (Example)



Major Area	Minor Area	Topic	Knowledge Fact	Knowledge Source
Intelligence	Source	Electronic Order of Battle (EOB)	The identification, location, and disposition of electronic systems of a military organization.	Space and Electronic Warfare Glossary
Intelligence	Targeting	Target	A geographical area, complex, or installation planned for capture or destruction by military forces. An area designated and numbered for future firing. A thing or place to be aimed at or hit.	DoD Glossary
Mission Planning	N/A	Desired Mean Point of Impact (DMPI)	The planned point whose coordinates are the arithmetic means of the coordinates of separate points of impact of a finite number of projectiles fired or released at the same aiming point under a given set of conditions.	Military Dictionary
Mission Planning	N/A	Rules of Engagement (ROE)	Directives issued by competent military authority which specify circumstances and limitations under which US forces will initiate or continue combat engagement with other forces.	DoD Glossary



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Activities Fe	OTM.	_ [_X
Activity	/ Form	
Activity ID Name Definition	Complete SAR This plan monitors the process of assigning the SAR, capturing the SAR picture, transmitting it to the MCS, and locate target(s) on the SAR image.	Steps Step Name SAR evaluated SAR planned * (choose step)
Additional Description		Refresh View Steps Form
Purposes	to locate target;to find nearby targets	Actions Action Name
Selection Issues	use ESM	* Take SAR Picture *
Failure Conditions	SAR camera malfunctioning, SAR not transmitted	Record: It I View Actions Form
Transition Conditions	active on At_SAR_Waypoint; SAR taken; SAR_Transmitted; SAR evaluated;revoked on target not found	Parameter Parameter Name ItargetID
References	Knowledge Team discussion - 7/11/2000	Refresh Record: It View Parameter Form
Record: I◀ ◀	6 ▶ ▶	

Integrated Knowledge Environment (IKE)



Step

Name Eligible Target Handled.

Description This goal marks event "new emitter detected, ready to

be rank ordered, prioritized, and assigned to a UCAV."

Preconditions Emitter must be in a kill box and on the Electronic

Order of Battle (EOB). Air Vehicle and weapons

available.

Desired Emitter will be rank ordered.

Outcomes Emitter may be prioritized and assigned.

Other effects Attack maneuvers may follow.

Recurrence Per new emitter detection.

Failure None.

Conditions



Activity

Name Recommend Plan.

Definition Evaluate eligible target, Rules of Engagement

(ROE), air vehicle state and recommend appropriate

script.

Purposes Initiate the mission planning process.

Selection Issues None.

Failure None.

Conditions

Transition None.

Conditions



Action

Name Call Mission Planner.

Definition Send recommended script.

Desired Operator accepted, populated script. Eligible target

Outcome promoted to target upon Operator acceptance.

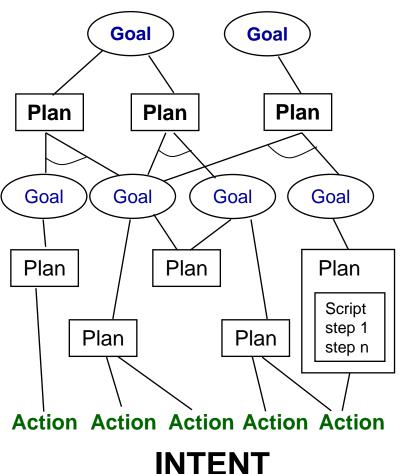
Preconditions None.

Failure Issues Task network communication failure.

Prohibitions None.

Plan-Goal Graphs Describe System Purposes



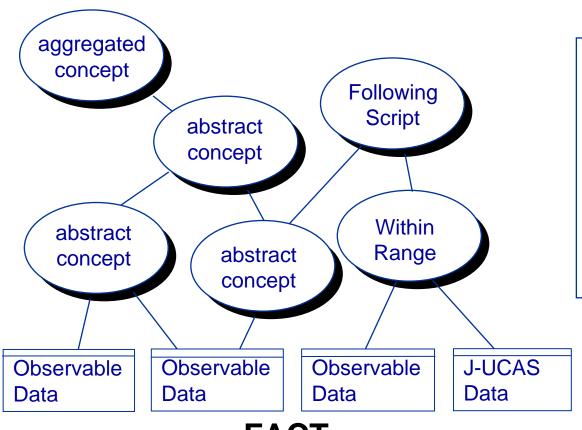


- The Plan Goal Graph
 - Models operator intent

- Plan-Goal Graph (PGG) a hierarchical decomposition of the mission.
- Rectangles represent plans which indicate "what" the operator is doing.
- Ellipses represent goals or "why" the operator is executing each plan.
- Plan requires all goals to be satisfied (an "and" node); goal requires only one plan to be successful (an "or" node).
- Plan may contain a script: a sequence of simple steps.
- Lowest level of decomposition (actions) represent primitive manipulations.
- Links contain knowledge in the form of constraints (e.g. within weapons range).

Concept Graphs Describe the Situation





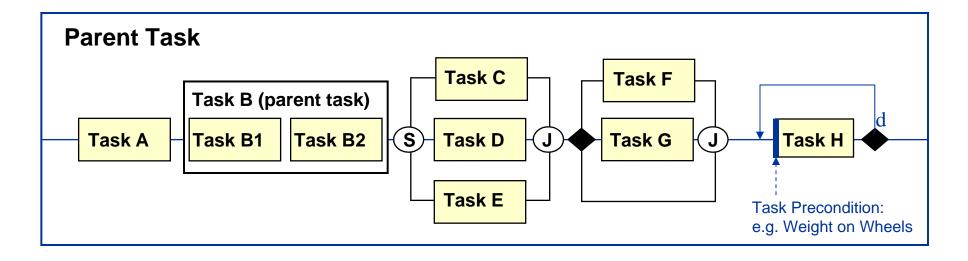
- Directed acyclic graph
- Increasing in abstraction and aggregation
- Links indicate dependencies
- Value propagation is dependency-directed

FACT

- The Concept Graph
 - Represents real world state

Task Network Node Types



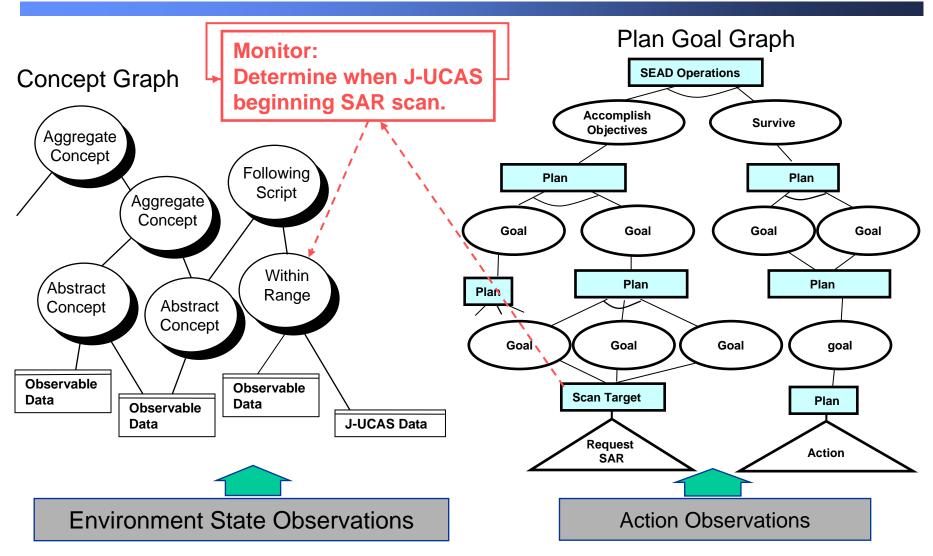


Task Network Similar to Management PERT Chart

- Represents computer tasks (1 100 mseconds)
- Represents operator tasks (1- 60 seconds)
- Network Topology represent task dependencies
- Task parameters include task importance and deadline

Monitors Link the Concept Graph and PGG



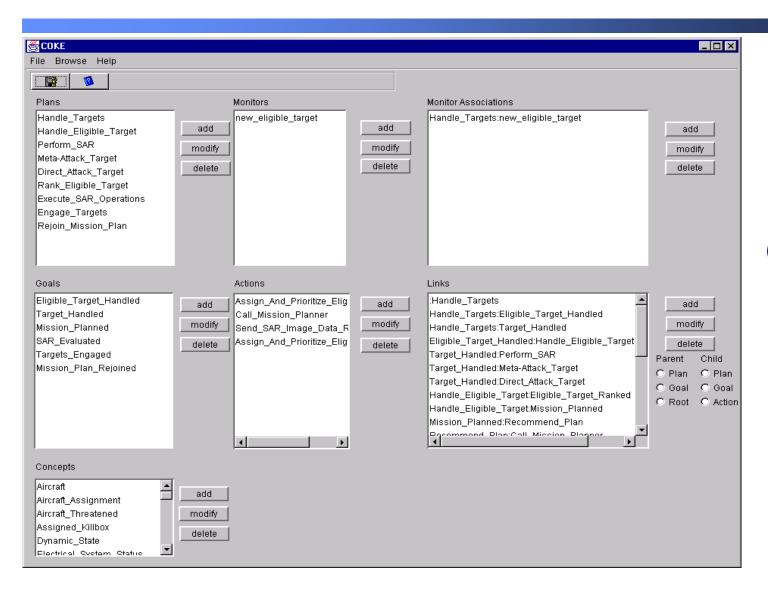




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Operational Knowledge Representation





Integrated Knowledge Environment (IKE)

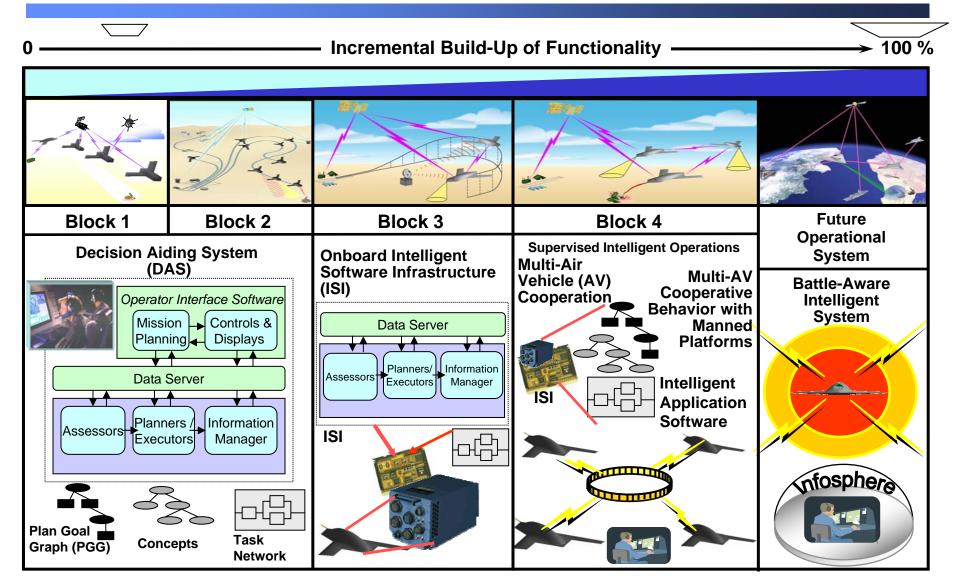
Knowledge Base (kb) File



//
MONITOR:
Monitor_Name: At_SAR_Waypoint //This monitor fires when the SAR waypoint is the next waypoint //and the distance is less than 750 meters.
Concept: Nominal_Trajectoty_Status
Attribute: actor VAR aircraftID Attribute: waypoint VAR nextWaypointNum
BEGIN_CONSTRAINT Operator: LESSER Left: context DOUBLE Nominal_Trajectory_Status:actor:distanceToNext Right: literal DOUBLE 750.0 END_CONSTRAINT
BEGIN_CONSTRAINT Operator: EQUAL Left: context INT Nominal_Trajectory_Status:actor:nextWaypointNum Right: value_list INT waypoint END_CONSTRAINT
END_MONITOR
//

Intelligent System Capability Development





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